



# Configuring the ROACH

In this step, we will program the ROACH with the [BOF\_FILE] and configure parameters like the ip address and port of the ROACH's 10GbE. After running the commands given below, the ROACH starts sampling the input signals given to iADC card and sends the data in UDP packets over 10GbE cable to CPU-GPU PC. The size of packet is 8k bytes with 4k bytes of data from each iADC input signal.

1. Open a terminal. If you are in [CTRL\_PC] no need to log in. Or else log in by using ssh.
2. [USER]@[CTRL\_PC]\$cd [PYTHON\_DIR]
3. [PYTHON\_DIR]\$./[CONFIG\_PY]

## Checking for packets

After configuring the ROACH to send data to CPU-GPU PC, we need to ensure that data is being received by the CPU-GPU PC. We will do this by using Wireshark software.

1. Open a terminal
2. [USER]@[GPU\_PC]\$sudo wireshark This opens the Wireshark window.
3. In the window opened click on 'Capture' and click on 'Interfaces' in the menu opened
4. Another window opens which shows information about all the interfaces available on the CPU\_GPU PC. The large numbers for 'packets' and 'packets/s' for the device corresponding to [TENGB\_IP] confirms the packets being sent on 10GbE. The 'packets' denotes the total number of packets and 'packets/s' denotes the packets per seconds. Now, close the Wireshark window.

## Creating shared memory

After confirming that packets are being received, we need to create shared memory to write the data into. Here, we create two shared memories with 4 buffers each of 256 MB. One shared memory for each of the input signals. The shared memories are represented by the keys 'bada' and 'cada'.

1. Open a terminal
2. [USER]@[GPU\_PC]\$cd [DELAY\_DIR]
3. [DELAY\_DIR]\$./ada.csh

This command actually destroys the shared memories, if any, created before and creates new shared memories. After running this command, there will be message printed which look as given below

*Destroyed DADA data and header blocks*

*Destroyed DADA data and header blocks*

*Created DADA data block with nbufs=4 bufisz=268435456*

*Created DADA header block with nhdrs = 8, hdrsz = 4096 bytes*

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*Created DADA header block with nhdrs = 8, hdrsz = 4096 bytes*

# Running the correlator program

After configuring the ROACH and creating the shared memory, we need to run the correlator. By running the commands given below, the CPU-GPU PC starts the correlator program, initialises the variables needed and waits for the shared memory data. After receiving the shared memory data, the data is copied into the GPU and correlation operation is done in GPU. After the correlation operation, the results are written back to CPU and finally written to a file named 'out.txt' in the [DELAY\_DIR] folder. Now follow the steps given below

1. Open a new terminal
2. [USER]@[GPU\_PC]\$cd [DELAY\_DIR]
3. [DELAY\_DIR]\$gmrt\_correlator -k ~/dada\_key\_list -g 1024 -q 4 268435456 2048 2 -w

After running this command, the program waits for data from the shared memories. In the command, the arguments give the following information to the process -k [filename] This argument provides the location and name of the file in which the shared memory keys are present

-g [number] This argument gives the number of FFTs that are to be computed parallelly on GPU. The optimised value is 1024

-q [count] This argument gives the number of streams to be run on GPU. The optimised value is 4. The -g and -q options combinedly gives that 1024 FFTs are parallelly computed using 4 streams on GPU.

The number 268435456 gives the integration time. This number gives the amount of data to be accumulated for one integration. The time to sample this amount of data at 400MHZ comes out to be 0.671088. So, our integration time is 0.671088. For every one integration the program writes the integrated output data to the file 'out.txt'.

The number 2048 gives the FFT size.

The number 2 gives the number of antennas or the number of input signals.

-w This argument informs the program to write the output to file 'out.txt' located in [DELAY\_DIR]

More information about the function can be known by command \$gmrt\_correlator -h.

# Running the packet capture program

As the correlator program is running and waiting for the data from shared memory, we need to capture the data over 10GbE cable and write it to the shared memories. By running the following commands, the CPU-GPU PC starts capturing the packets over the 10GbE, unpacks the packets and writes the data from each signal to corresponding shared memories. As mentioned earlier, each packet is of 8k bytes with 4k bytes from each input signal.

1. Open a terminal
2. [USER]@[GPU\_PC]\$cd [DELAY\_DIR]
3. [DELAY\_DIR]\$gmrt\_udpdb\_multi -i [TENGB\_IP] -p [TENGB\_PORT] -H ~/header 2 bada cada 0 0 -n 10

After running this command, the program starts capturing packets, unpacks the data and writes the data to corresponding shared memories. The arguments give the following information to the process

-i [ipaddress] ipaddress of the interface from which the data is being received

-p [port] port that is open for UDP packets to be received

-H [filename] location and name of the header file. This header file gives the information regarding the sampling frequency, number of bits per sample etc. The file contents can be viewed using the command `$cat ~/header`

The number 2 in the command arguments gives the no. of antennas or the input signals

bada and cada are the keys of shared memories to which the data is to be written

The numbers 0 0 are the delays for each input. We will come back to this later. For now just keep them 0 0

-n [secs] time for which the data needs to be received. After the amount of time given using this argument the packet capturing program and the correlator program stops.

[Note: If the packet capturing program does not stop after the amount of time given using -n option, then, first stop the packet capturing program by `ctrl+c`, and go to the terminal started in step 4 and type the command `./dda.csh` This command actually destroys the shared memories and stops the correlator program.]

More information can be obtained by using the command `$gmrt_udpdb_multi -h`

While running this program, the following messages will be printed on the screen. [Note: The numbers may vary]

*[2011-09-08-17:04:57] Using current time for UTC\_START = 2011-09-08-11:34:57*

*[2011-09-08-17:04:57] B/sample=2.000000, TSAMP=0.002500, B/second=800000000.000000*

*[2011-09-08-17:04:57] header marked filled*

*start of udpdb\_multi: 1315481697*

*timestamps 1315481697 0*

*[2011-09-08-17:04:57] stream[0] delay offset -0.0000366729982488 s -> -14669 bytes -> 0 bytes*

*[2011-09-08-17:04:57] stream[1] delay offset -0.0000008345460287 s -> -333 bytes -> 0 bytes*

*[2011-09-08-17:04:57] T=0.0, R=0.0, D=0.0 MiB/s bsleeps=0 dropped=0*

*[2011-09-08-17:04:57] START: received packet 477233637*

*timestamps 1315481697 671088*

*[2011-09-08-17:04:58] stream[0] delay offset -0.0000366720269085 s -> -14668 bytes -> 0 bytes*

*[2011-09-08-17:04:58] stream[1] delay offset -0.0000008345475635 s -> -333 bytes -> 0 bytes*

*[2011-09-08-17:04:58] T=537.0, R=537.0, D=0.0 MiB/s bsleeps=1106278 dropped=0*

.....

## **Analysing the result using tax program**

The correlator program writes the results to output file “out.txt” located in [DELAY\_DIR] folder. The results are analysed using the software Tax(built in GMRT). Follow the steps given below

1. Open a new terminal
2. [USER]@[GPU\_PC]\$cd [TAX\_DIR]
3. [TAX\_DIR]\$./xtrgsb32\_rawsamp -v [DELAY\_DIR]/out.txt -c 1,2047 -t 0 This command will open a window which looks as below

The arguments given to this command represents

-v [filename] the output filename to which the correlation output results are written

-c [start,final] this argument gives the channel range to be plotted.start and final values can be anywhere between 1 to 2047 as our FFT size is 2048. But, with final > start

-t [timestamp] this argument gives the output of which integration to be plotted. It can be any number in between 0 to t, where t is given by  $t = \{ [\text{time given in packet capture program}] / [\text{integration time}] \} - 1$ , here it is 13

In the window opened click on 'C00','C01','Amplitude' and then click 'Plot'. A window opens which shows the self amplitudes of both the signals. The plot corresponding to 'C00-USB-130' is of ADC input 'i' and the plot corresponding to 'C01-USB-130' is of ADC input 'q'.

The x-axis is frequency channels and the y-axis is power. Bandwidth is 200MHZ as sampling frequency is 400MHZ.

4. Close the plot window and click 'quit' on tax window.

5. Now we will plot the cross amplitude and phase using the command given below

```
[TAX_DIR]$./xtrgsb32_rawsamp -v [DELAY_DIR]/out.txt -c 1,2047 -t 0 -r C00 -n 1
```

This command is similar to the previous command with extra arguments.

-r [antenna] this argument gives the reference antenna with which cross is to be plotted

-n 1 this argument gives information that the cross amplitude to be normalised

After running this command a window similar to tax window opens with only 'C01' option.Click on 'C01' and click on 'Plot'. A window opens which shows the cross amplitude(normalised) and cross phase.

## Offline testing

Offline testing is for processing the raw data signals that are captured and are already present on the disk. It can be done in 3 steps

### Creating a file with the names of raw data files

Enter the file names of raw data files on disk into a file named file.list. This can be done by vim editor.

1. Open a terminal

2. [USER]@[GPU\_PC]\$cd [DELAY\_DIR]

3. \$vim file.list

Enter the names of [RAW\_DATA\_FILES] in separate lines and save it. For example purpose, file\_example.list exists which contains the names of raw data files from noise source.

### Running the correlator program

```
[DELAY_DIR]$gmrt_correlator -f file.list -g 1024 -q 4 419430400 2048 2 -w
```

In this command the -f option gives the file which contains the names of raw data files. Everything else is similar to the step5.

## **Analysing the result**

Refer to step7:Analysing the result using tax program.But with -t option always 0.